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TITLE OF THE INVENTION

ACTIVE RESISTIVE SUMMER FOR A TRANSFORMER HYBRID

BACKGROUND OF THE INVENTION

10 Field of the Invention

The present invention relates generally to transmitting and receiving electrical signals through communication channels, such as a gigabit channel. In particular, the present invention relates to a transmit canceller that removes transmit signals from receive signals in such communication channels.

Background and Related Art

- A gigabit channel is a communications channel with a total data throughput of one gigabit per second. A gigabit channel typically includes four (4) unshielded twisted pairs (hereinafter "UTP") of cables (e.g., category 5 cables) to achieve this data rate. IEEE Standard 802.3ab, herein incorporated by reference, specifies the physical layer parameters for a 1000BASE-T channel (e.g., a gigabit
 - channel).

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As will be appreciated by those skilled in the art, a UTP becomes a transmission line when transmitting high frequency signals. A transmission line can be modeled as a network of inductors, capacitors and resistors, as shown in Figure 1. With reference to Figure 1, G is normally zero and $R(\omega)$ is complex due to skin effect. $R(\omega)$ can be defined by:

$$R(\omega) = k_s(1+j)\sqrt{\omega}, \tag{1}$$

where k_R is a function of the conductor diameter, permeability, and conductivity. The characteristic impedance of the line is defined by:

$$Z_{\circ} = \sqrt{\frac{R(\omega) + j\omega L}{G + j\omega C}},$$
 (2)

and at high frequencies, Z_0 becomes approximately $\sqrt{L/C}$ or approximately 100 ohms in a typical configuration. When properly terminated, a UTP of length d has a transfer function H that is a function of both length (d) and frequency (ω) :

$$H(d,\omega) = e^{dY(\omega)}, \tag{3}$$

20 where

$$\gamma\omega = \sqrt{(R(\omega) + j\omega L)(G + j\omega C)}, \tag{4}$$

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and substituting Equations 1 and 4 into Equation 3, and simplifying, approximately yields:

$$H(d,\omega) \approx \exp \left\{ d \left[\frac{k_{s}}{2} \sqrt{\frac{\omega L}{C}} + j \left(\omega \sqrt{LC} + \frac{k_{s}}{2} \sqrt{\frac{\omega L}{C}} \right) \right] \right\}.$$
 (5)

5 Equation 5 shows that attenuation and delay are a function of the cable length d.

A transmission path for a UTP typically includes a twisted pair of cables that are coupled to transformers at both a 10 near and far end, as shown in Figure 2. A transceiver at each end of the transmission path transmits and receives via the same twisted pair. A cable typically includes two patch cords totaling less than 10m, and a main section of 100m or even longer. The transmitters shown in Figure 2 15 are modeled as current sources. The near end current source supplies a current I .. The near end transmit voltage (e.g., $I_{tx}R_{tx}$) is detected and measured across resistor R_{tx}. A receive signal V_{rcv} (e.g., a signal transmitted from the far-end transceiver) is also detected 20 and measured across resistor R_{tx} . Hence, V_{tx} includes both transmit $(I_{tx}R_{tx})$ and receive (V_{rcv}) signals. Accordingly, the signal V_{rev} (e.g., the signal from Transceiver B)

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received at Transceiver A can be obtained by taking the difference between the transmit voltage and the measured voltage $V_{\tau x}$, as follows:

$$V_{rev} = V_{tx} - I_{tx}R_{tx}. \tag{6}$$

Conventional solutions for removing transmit signals from receive signals often employ known transconductor ("Gm") 10 summing stages or other current based methods. As will be appreciated, these methods often introduce signal distortion into the receive signal. Also, some transconductors have a limited signal dynamic range. Accordingly, conventional methods are often inadequate for 15 applications requiring signal recovery. Additionally, known summing circuits, such as weighted summers using operational amplifiers, have not heretofore been modified to accommodate the intricacies associated with canceling transmit signals or regulating baseline wander (described below). A known weighted summer is discussed in Chapter 2 20 of "Microelectronic Circuits, Third Edition," by A.S. Sedra and K.C. Smith, 1991, incorporated herein by reference.

As will be appreciated by those skilled in the art, the receive signal V_{rev} typically contains additional components, due to baseline wander, echoes and crosstalk, for example.

5 Baseline wander is preferably corrected for when transmitting and receiving signals over transmission lines.

Removing DC components from a receive signal using transformer coupling can cause baseline wander. As will be appreciated by those skilled in the art, baseline wander represents a deviation from an initial DC potential of a signal.

"Echoes" typically represent a residual transmit signal caused by reflections that appear in the receive signal. Echoes can cause undue interference depending on the size of the reflection.

Capacitive coupling between the channels, as shown in Figure 3, causes crosstalk. Four channels TX1-TX4 are shown in Figure 3. The capacitive coupling between TX1 and each of TX2, TX3 and TX4 are modeled by capacitors C₁₋₂, C₁₋₃, C₁₋₄, respectively. The capacitive coupling forms a high-pass filter between channels and therefore crosstalk contains mostly high frequency components. As will be

appreciated by those skilled in the art, normally only the near-end crosstalk (NEXT) needs to be considered, since crosstalk is usually small and the transmission line provides further attenuation of the far-end crosstalk (FEXT).

Accordingly, there are many signal-to-noise problems to be solved in the art. Hence, an efficient transmission canceller is needed to remove a transmit signal from a receive signal without introducing excess signal distortion. An electrical circuit is also needed to subtract a transmit signal from a receive signal. There is a further need of an electrical circuit to correct baseline wander.

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SUMMARY OF THE INVENTION

The present invention relates to a transmit signal canceller for use in a transformer hybrid. Such a hybrid includes a junction for transmitting and receiving signals. In the present invention, an active resistive summer can be

used to cancel a transmit signal from a receive signal.

According to the invention, an electrical circuit in a communications channel is provided. The electrical circuit includes an active resistive summer having: (i) an input for a composite signal, the composite signal including a transmission signal component and a receive signal component, (ii) an input for a replica transmission signal, and (iii) an output for a receive signal which includes the composite signal minus the replica signal.

10 According to an another aspect of the present invention, a transmit signal canceller in a communication channel is provided. The channel includes a first transceiver for transmitting and receiving signals and a replica transmitter for generating a replica transmission signal 15 input. A composite signal at a rear end includes a transmission signal of the first transceiver and a received signal of a second transceiver. The transmit canceller includes: (i) an operational amplifier having a positive input terminal, a negative input terminal, and an output 20 terminal; (ii) a feedback element in communication with the negative input terminal and the output terminal; (iii) a first input resistor in communication with the negative input terminal and the measured signal input; (iv) a second input resistor in communication with the negative input

terminal and the replica signal input; and (v) a predetermined voltage source in communication with the positive terminal of the operational amplifier. The receive signal is an output at the output terminal of the operational amplifier.

According to still another aspect of the present invention, a communication system including a first transmission channel with a first end and a second end is provided. 10 first end couples to a first transformer and the second end couples to a second transformer. A first transceiver transmits and receives signals via the first transformer and a second transceiver transmits and receives signals via the second transformer. A first signal is supplied at the 15 near end. The first signal includes a transmission signal component of the first transceiver and a receive signal component of the second transceiver. The communications system includes: (i) a replica transmitter that generates a replica of the transmission signal component of the first 20 transceiver; (ii) a filter to filter the replica signal; (iii) an active resistive summer receiving the first signal, and the filtered replica signal as inputs to reduce the transmission signal component at an output of the active resistive summer.

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According to still another aspect of the present invention, a method of correcting baseline wander in a receive signal in a communications channel having a near and far end is provided. The channel includes a first transceiver at the near end and a second transceiver at the far end, each to transmit and receive signals. The method includes the steps of: (i) providing a composite signal, the composite signal including a transmission signal of the first transceiver and a receive signal of the second transceiver; (ii) generating a replica of the transmission signal; (iii) subtracting the replica signal from the composite signal through an active resistive summer; and (iv) providing a baseline correction current into the active resistive summer.

These and other objects, features, and advantages of the present invention will be apparent from the following description of the preferred embodiments of the present invention.

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BRIEF DESCRIPTION OF THE DRAWINGS

The details of the present invention will be more readily understood from a detailed description of the preferred embodiments taken in conjunction with the following figures.

Figure 1 is a circuit diagram illustrating a transmission line model.

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Figure 2 is a circuit diagram illustrating a transmission path across a twisted pair of cables, the cables being coupled to transformers at each end.

15 Figure 3 is a diagram-illustrating crosswalk between channels in a gigabit channel.

Figure 4 is a block diagram illustrating a system overview of a communications channel.

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Figure 5 is a circuit diagram illustrating a transmitter.

Figure 6 is a graph illustrating a transmit signal.

Figure 7 is a graph illustrating a composite signal with echoes.

5 Figure 8 is a circuit diagram illustrating a replica transmitter.

Figure 9 is a graph illustrating a receive signal.

10 Figure 10 is block diagram illustrating a low-pass filter.

Figure 11 is a circuit diagram illustrating an active resistive summer.

15 Figure 12 is a circuit diagram illustrating an error detection circuit.

Figure 13 is a circuit diagram illustrating a low-pass filter.

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Figure 14 is a circuit diagram illustrating a conventional voltage controlled current source.

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DETAILED DESCRIPTION OF THE PRESENTLY PREFERRED EMBODIMENTS

The preferred embodiments will be described with respect to

a gigabit channel, as used, for example, in an Ethernet
network; and to electrical circuits associated with
separating transmit and receive signals in such a gigabit
channel. The preferred embodiments will also be described
with respect to baseline wander correction in such a

gigabit channel. However, as will be appreciated by those
skilled in the art, the present invention is also
applicable to other transmission channels, and to other
electrical circuits having applications requiring
cancellation of transmit signals, for example.

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Figure 4 is a block diagram illustrating principle
components for one of the four channels in a preferred
gigabit channel configuration for use in an Ethernet
network. As illustrated in Figure 4, a vertical dashed
line divides analog and digital processing components. The
analog components preferably include a transmitter ("XMTR")
l, replica transmitter ("Replica XMTR") 2, transmit
canceller 3, baseline correction module 4, low pass filter
("LPF") 5, analog-to-digital converter ("ADC") 6, and

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phase-lock loop ("PLL") 7. A known PLL can be used with the present invention.

transmitter encoder 10, echo module 11, NEXT cancellers 1214 to assist in removing echoes, synchronization module 15,
FIR (Finite Impulse Response) equalizer 16 and a DFE
(Decision Feedback Equalizer) 17 to equalize a receive
signal, and a Viterbi module 18. The digital processing
components also include baseline correction modules 19 and
20 to correct residual baseline wander. A timing recovery
module 21, an error correction detector 22 (described in
further detail below), and summing junction 23 are also
shown. The individual digital components designated by
blocks in Figure 3 are all well known in the communication
arts, and their specific construction and operation are not
critical to the operation or best mode for carrying out the
present invention.

The analog "front-end" components shown in Figure 4 will now be described in even further detail. The front-end analog components are preferably designed and constructed via customized integrated circuits. However, as will be appreciated by those skilled in the art, the inventive

circuits and corresponding configuration could also be realized using discrete components as well.

As illustrated in Figure 5, transmitter 1 preferably includes a current-source I_{tx} that generates a transmit signal over a resistor R_{tx} . An appropriated value for resistor R_{tx} can be selected to match the line impedance, for example. In one preferred embodiment, a resistor center tap is set to 2.5 volts so the transmitter 1 effectively sees a differential impedance of 25 ohms. Preferred performance specifications for the transmitter 1 are further detailed in Table 1, below.

An impulse transmit signal can be generated from a unit

15 square pulse of 1T width filtered by a one-pole, low-pass
filter (not shown) with a cutoff frequency between 85MHz
and 125MHz. Slew-rate control can also be used to limit
the rise and fall times and thus reduce the high frequency
components of a transmit signal. Of course, any transmit

20 signal preferably fits into the transmit template provided
by the IEEE 802.3ab Standard. An ideal transmit pulse is
shown in Figure 6.

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A measured voltage V_{tx} across R_{tx} (Figure 5) is shown in Figure 7. The measured signal V_{tx} contains interference caused by line reflections (e.g., echoes). The reflections are caused by impedance discontinuity due to impedance mismatch between different cables. For example, a large reflection pulse at 60ns as shown in Figure 7 corresponds to a reflection from the impedance discontinuity at an adapter connecting a 5m patch cord to a 100m cable. The magnitude of the echoes can be significant when compared to the magnitude of the receive signal at a long line length, and therefore, echo cancellation, as provided by the NEXT cancellers 12-14 shown in Figure 4, is employed.

A receive signal V_{rev} (e.g., a signal received from a far-end transceiver) is also measured across resistor R_{tx}, as shown in Figure 5. Accordingly, the near end transmit signal (I_{tx}R_{tx}) is preferably canceled or reduced from the composite signal V_{tx} in order to effectively recover the far-end received signal V_{rev}. This type of active cancellation can be accomplished with a replica transmit signal V_{txr}. Accordingly, a replica transmitter 2 (to be described below) is provided to generate a signal V_{txr} to be subtracted from the measured signal V_{tx}, thus, effectively reducing the transmit signal (I_{tx}R_{tx}).

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A receive signal x(t) transmitted with pulse amplitude modulation ("PAM") is define by:

$$\mathbf{x(t)} = \sum_{n=1}^{\infty} a_n p(t-nT), \tag{7}$$

where a, is the transmit symbols and p(t) is the channel pulse derived by convoluting an impulse transmit pulse with a channel response defined by Equation 5. The receive signal for a 100m cable is heavily attenuated by the transmission line and the pulse width is dispersed, as shown in Figure 9. A 100m UTP delays the signal by about 550ns. Signal equalization preferably uses high frequency boosting via the FIR 16 to remove precursor intersymbol interference ("ISI") and to insert a zero crossing for timing recovery 21. The DFE 17 is used to remove postcursor ISI.

The receive signal's elongated tail results from transformer coupling (e.g., a high-pass filter) with a time constant (e.g., L/R) typically on the order of microseconds. Since the receive signal contains little or no average DC energy, the negative tail has the same amount of

energy as the positive pulse. In this regard, the signal's area integral is zero. In a typical example, a tail can last over 10µs with a magnitude of no more than 0.5mV. The long tail causes any DC bias to drift back toward zero,

5 which can lead to baseline wander. As will be appreciated, this response time is too long to be practically removed by a digital equalizer, but the response is slow enough to be cancelled using a slow integrator, for example. The baseline wander canceller 4 is preferably decision directed to minimize the error defined by the difference between the equalized value and it's sliced value, as discussed below.

As illustrated in Figure 8, the replica transmitter 2 includes a current source I_{txr}. I_{txr} is coupled to a voltage

15 V through resistors R, as shown in Figure 8. In a preferred embodiment, R is 100 ohms and V is about 2.5 volts. The replica signal V_{txr} is preferably filtered through a known low-pass filter to obtain a low-pass replica signal ("V_{txr1}"), as shown in Figure 10. Replica

20 signal V_{txr} can also be inverted in a known manner to produce -V_{txr}. The preferred performance specifications for the transmitter 1 and replica transmitter 2 are shown in Table 1.

Table 1: Transmitter and Replica Performance Specifications

Parameters	Specifications
Transmit Current	+/- 40mA
Replica Transmit Current	4 of transmit current
Number of levels	16 (not including 0)
Number of sub-units	8 (sequentially delayed)
Transmit Profile	[1 1 2 2 1 1], w/~1ns delay
Replica Transmit Profile	[1 1 3 3], w/~1ns delay
R_{κ}	100Ω

A transmit signal canceller 4 is illustrated in Figure 11. The transmit canceller 4 removes the transmission signal $(I_{tx}R_{tx})$ from the measured (or detected) transmit V_{tx} signal. In particular, the transmit canceller includes an active resistive summer that provides a large input dynamic range and stable linearity characteristics, while removing (e.g., reducing or canceling) the unwanted transmit signal component.

As illustrated in Figure 11, the active summer includes an operational amplifier ("op-amp") with inverting feedback. The op-amp is preferably constructed using integrated circuits in a known manner. The summer receives V_{txrl} , V_{tx} , $-V_{txr}$, I_{cma} , and I_{bl} as input signals. I_{bl} is a baseline wander control current, and I_{cms} is a common-mode shift current, each as further discussed below.

As will be appreciated by those skilled in the art, a transformer typically has high-pass characteristics. Accordingly, replica signal -V_{txr} is combined (e.g., subtracted via the active resistive summer) with the low pass replica signal V_{txrl} to produce a high-pass replica signal. As an alternative configuration, V_{txr} could be filtered through a known high-pass filter prior to the transmit canceller 3 stage.

Returning to Figure 11, receive signal V_{rev} is determined from the following relationships.

Let:

Vi = voltage for the op-amp's positive terminal;
$$V_1' = V_{txr1};$$

$$V_2 = V_{tx};$$

$$-V_3 = -V_{txr};$$

$$i_4 = I_{cms}; \text{ and}$$

$$i_5 = I_{b1}.$$

Then:

(i)
$$i_1 + i_2 - i_3 - i_4 - i_5 = i_0$$
; and

(ii) $\frac{V_1 - V_i}{R_1} = i_1$; $\frac{V_2 - V_i}{R_1} = i_2$; $\frac{V_i - V_1}{R_1} = i_3$; $\frac{V_i - V_{rcv}}{R_r} = i_0$.

$$\Rightarrow \frac{V_1 - V_i}{R_1} + \frac{V_2 - V_i}{R_1} - \frac{V_i + V_2}{R_1} - i_4 - i_5 = \frac{V_i - V_{rcv}}{R_r}$$

$$\Rightarrow \frac{V_1 + V_2 - V_3 - 3Vi}{R_1} - i_1 - i_2 = \frac{Vi - Vrcv}{Rr}$$

$$\Rightarrow \frac{R_r}{R_1} (V_1 + V_2 - V_3 - 3Vi) - i_1 \cdot R_r - i_3 \cdot R_r = Vi - Vrcv$$

$$\Rightarrow \frac{R_r}{R_1} (V_1 + V_2 - V_3 - 3Vi) - R_r i_2 - R_r i_3 - Vi = -Vrcv$$

$$V_{rcv} = V_1 - \frac{R_r}{R_1} (V_1 + V_2 - V_3 - 3Vi) + R_r (i_2 + i_3)$$
(8)

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Substituting the input signals for their placeholders yields the definition for V_{rov} , as follows:

$$V_{rev} = Vi - \frac{R_r}{R_s} (Vtxrl + Vtx - Vtxr - 3Vi) + R_r(Icms + IbI).$$
 (9)

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The gain is preferably set between 0.75 and 1 (e.g., R_r/R_1 equals 0.75 to 1). For a small signal analysis, Vi can be set to zero (0). Also, as will be appreciated by those skilled in the art, in a fully differential circuit, Vi effectively drops out of the equations since $V_{rev} = V_{rev}^{(+)} - V_{rev}^{(-)}$. As discussed, V_{txr1} and $-V_{txr}$ are combined through the active summer to provide a high-pass replica signal (" V_{txrh} "). The receive signal V_{rev} can then be recovered as shown by Equation 9.

Preferred transmit canceller specifications are detailed in Table 2, below.

Table 2: Transmit Canceller Performance Specifications

Parameters	Specifications
Input Dynamic Range	+/-2.5V(diff.) for transmit signal
Output Dynamic Range	+/-1V(diff.)
Input impedance	High, ~10k.
Output impedance	Low
Cutoff frequency	Greater than 31.5 Mhz
DC Gain	0.85 -dependent on the LPF 5 and ADC 6 characteristics (Figure 4)
Power	25 mw, including LPF 5 (Figure 4)
\mathbb{R}_{t}	8.5 KΩ; or 7.5KΩ for increased attenuation
Vi	2.0 volts
R,	10ΚΩ

A known current mode circuit, e.g., a voltage controlled current source (VCCS) as shown in Figure 14, with feedback preferably sets the summer input current-mode voltage (V_{cm}).

10 Of course, other known current mode circuits could be employed with the present invention. This current-mode circuit shifts the common-mode of both the transmit and replica transmit signals. The input to the op amp (V_{aip}, V_{sin}) is compared against the desired op amp output common-mode voltage (V_a):

$$V_d = (V_{aip} - V_{cm}) + (V_{ain} - V_{cm}).$$
 (10)

Then, the common-mode shift current can be determined from:

$$I_{cms} = V_d g_m + I_0, \qquad (11)$$

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where g_m is a transconductance and I_o is an offset current. An appropriate transconductance and offset current can be selected by setting $V_{cm} = I_{cmp}R_F = V_dg_mR_F + I_0R_F$, to ensure a proper common-mode voltage seen by the op amp inputs. In this manner, the common mode shift current I_{cms} can be regulated to pull down the common mode voltage of the operational amplifier as needed.

Baseline wander current I_{b1} is also "summed" by the active

resistive summer, as shown in Figure 11, to correct

baseline wander. Approximately ninety percent (90%) of all

system baseline correction can be obtained through the

active summer. The remaining baseline residual can be

digitally corrected through an equalizer, for example. As

will be appreciated, the Figure 11 topology allows the

current sources (I_{b1} and I_{cme}) to each have a fixed output

voltage, thus, minimizing current deviation due to finite

output resistance.

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The baseline wander correction module 4 preferably corrects for baseline wander using a decision-directed method, such as a discrete integrator. The decision-directed method can be implemented with a known charge pump, where the pump sign (e.g., +1/-1) is determined digitally using an error 5 between the equalized baseline signal (y_k) and a sliced baseline signal $(\hat{y_k})$, as shown in Figure 12. As will be appreciated by those skilled in the art, the expected error value (e.g., $E[e_k]$) is ideally driven to zero. The charge 10 pump is preferably pumped up or down based on the error value. For example, a positive error implies that a negative value should be input into the charge pump. For a negative error, a positive value should be input into the charge pump. The charge pump preferably has at least two current settings to regulate I_{bl} . Of course, a charge pump 15 with many current settings could be used to obtain finer baseline correction control.

The preferred baseline wander correction performance 20 specifications are further detailed in Table 3, below.

Table 3: Baseline Wander Correction Specification

Parameters	Specifications
Output Dynamic Range	$+/-100$ uA (diff.), ($+/-1$ V/ R_1 , $R_1 = 10$ k Ω)
Output impedance	High
Integration Factors	2 mV/T, 4 mV/T
Bandwidth	> 100MHz

A second-order low-pass filter, as shown in Figure 13, is

5 cascaded after the summer to preferably flatten the
frequency response out to about 31.25MHz (<1dB). A minimum
overall attenuation of 20dB at 125MHz is desirable for the
low pass filter. In a sampled system, some aliasing beyond
Nyquist frequency (or excess bandwidth) is acceptable, but

10 minimum aliasing is allowed at the sampling frequency. The
transmitted data is preferably band-limited to the Nyquist
rate.

Preferred performance characteristics of the low pass 15 filter 5 are further detailed in Table 4, below.

Table 4: LPF Performance Specification

Parameters	Specifications
Input Dynamic Range	+/-1V(diff.)
Output Dynamic Range	+/-1V(diff.)
Input impedance	High, ~10k.
Output impedance	Low
Cutoff frequency	50-60Mhz.
Q (2nd order)	~1
Input impedance	High, ~10k.
Output impedance	Low, <100
DC gain	1

As an alternative arrangement, a third-order Sallen and Key low pass filter as disclosed in a co-pending application by the same inventor of this application, titled "CALIBRATION CIRCUIT," filed concurrently herewith, and hereby incorporated by reference, could be used as filter 5. Similarly, the calibration circuit disclosed therein could also be used to calibrate the low pass filter 5.

Analog-to-digital converters are well know in the art. As will be appreciated, the ADC 6 resolution is often determined by system digital processing requirements. In a preferred embodiment, the Viterbi detector 18 requires an effective 7-bit resolution. Residual baseline wander, echoes, and crosstalk increase the dynamic range by about 200-300mV, which increases the required resolution. The reduction in dynamic range due to insertion loss for a 100m cable is approximately 40%. Accordingly, an 8-bit

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resolution is preferred.

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The preferred ADC performance specifications are further detailed in Table 5, below.

functions.

Table 5: ADC Performance Specification

Parameters	Specifications
Resolution	8-bits minimum.
Sampling frequency	125MS/s
Source Output Impedance	Low, ~200-400Ω

5 Thus, a transmit canceller including an active resistive summer has been described. Such an active resistive summer has not heretofore been developed for applications such as canceling signals in gigabit channels. Correcting baseline wander through such an active resistive summer has also been described herein.

While the present invention has been described with respect to what is presently considered to be the preferred embodiments, it will be understood that the invention is not limited to the disclosed embodiments. To the contrary, the invention covers various modifications and equivalent arrangements included within the spirit and scope of the appended claims. The scope of the following claims is to be accorded the broadest interpretation so as to encompass all such modifications and equivalent structures and

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For example, while preferred circuit configurations and component values have been described, it will be understood that modifications could be made without deviating from the inventive structures. For example, values for the feedback and input resistors R_f and R_i could be changed to obtain higher or lower gains. Also, an active resistive summer could be constructed to sum only the measured signal V_{tx} and the replica signal V_{txr} (or a high-pass version of the replica), for example. Additionally, while the communication channel has been described with respect to a twisted pair of cables, the invention may also be practiced with other communication channels such as optical and wireless channels. Moreover, this invention should not be limited to gigabit transmission rates and can be practiced at any transmission rate requiring the signal processing characteristics of the invention. Of course, these and other such modifications are covered by the present invention.